

# NHUT LE

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**SUMMARY** Computer Vision Engineer with experience in 3D computer vision, machine learning, and deep learning. Proficient in Python, OpenCV, and PyTorch with a strong mathematical background. Passionate about solving problems in computer vision and computer graphics

## EXPERIENCE

**Research Assistant** Aug 2024 - present

*Bina Lab, Lehigh University, Bethlehem, PA*

- Research 3D methodologies and machine learning to support disaster-affected areas

**Computer Vision Engineer** Oct 2020 - Oct 2023

*Sturfee Inc., Milpitas, CA*

- Develop, prototype, and enhance methods for 3D reconstruction and precise localization in the 3D prior map using Structure-from-Motion (SfM) and Multi-View Stereo (MVS) techniques, resulting in improving outdoor Visual Positioning System (VPS) and enabling indoor VPS
- Implement and optimize RGBD integration algorithms to reconstruct 3D point clouds and meshes, such as using TSDF volume integration and optimizing RGBD poses
- Work with deep learning networks for 3D semantic segmentation
- Proficient in 3D manipulations such as mesh texturing, texture baking, bundle adjustment, and UV unwrapping

## EDUCATION

Lehigh Univesity                      Ph.D in Computer Science                      Aug 2024 - present

Portland State University                      Master of Science in Computer Science                      Sep 2018 – Aug 2020

Portland State University                      Bachelor of Science in Computer Science                      Jan 2015 – Jun 2018

## PERSONAL PROJECTS

**Deep Image Homography Estimation** Jul 2020

- Re-implemented the paper “Deep Image Homography Estimation” from scratch
- Estimated a 4-point homography parameterization mapping the four corners from an image into the second image
- Achieved an average corner error of 6.003 for the train set and 6.034 for the validation set which is lower than from the original paper

**Deep Essential Matrix without Correlations** Jun 2020

- Utilized a convolutional network to estimate the essential matrix between two images of a monocular camera in the epipolar geometry directly, without detecting feature points (correlations)
- Achieved a small error rate of 5%

## SKILLS AND INTERESTS

**Skills:** Proficient in Python, C++, PyTorch, OpenCV, scikit-learn, scikit-image, matplotlib, Git, NumPy, Open3D, and Trimesh. Experienced with VSCode and PyCharm

**Interests:** Computer vision, 3D reconstruction, 3D localization, camera calibration, deep learning

## AWARDS

International Achievement Scholarship    Portland State University                      2015-2018

The second place                      Dong Thap Olympiad for High School Student                      2010 and 2011  
Individual Contest in Math - Vietnam

Gold Medal                      Mekong Delta Olympic in Math - Vietnam                      2010

Silver Medal                      Olympic 30/4 in Math - Vietnam                      2009